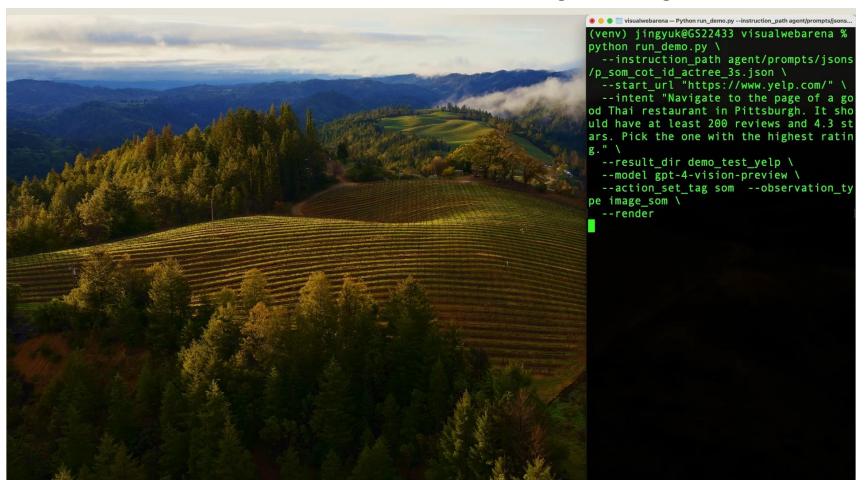
Benchmarks and Tree Search for Multimodal LLM Web Agents

Daniel Fried



Language Technologies Institute

Carnegie Mellon University **Task**: Navigate to the page of a good Thai restaurant in Pittsburgh. It should have at least 200 reviews and 4.3 stars. Pick the one with the highest rating.



Why Web Agents?

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Why Web Agents?

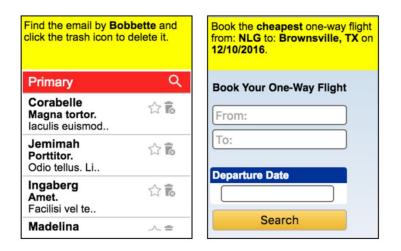
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Details Info			
PC ID	State	DNS hostnames	DNS resolution
🗇 vpc-0 33	@ Available	Enabled	Enabled
Tenancy	DHCP option set	Main route table	Main network ACL
Default	dopt-0;	rtb-06 06	acl-05 .56
Default VPC	IPv4 CIDR	IPv6 pool	IPv6 CIDR (Network border group)
No	10.0.0/17	-	-
Network Address Usage metrics	Route 53 Resolver DNS Firewall rule groups	Owner ID	
Disabled	-	0	
VPC Show details	Subnets (9)	Route tables (8)	Network connections (3)
Your AWS virtual network	Subnets within this VPC	Route network traffic to resources	Connections to other networks
channy-vpc	us-west-2a	channy-rtb-private6-us-west-2c	channy-igw
	channy-subnet-public1-us-west-2a	channy-rtb-private4-us-west-2a	channy-nat-public1-us-west-2a
	Channy-subnet-private4-us-west-Za	rtb-06 16	channy-vpce-s3
map	channy-subnet-private1-us-west-2a	channy-rtb-public 🖸	
The new resource map helps you visualize the resources in your VPC. It shows your VPC,	us-west-2b	3 subnet associations 2 routes including local	
subnets, route tables, internet	channy-subnet-public2-us-west-2b	channy-rtb-private5-us-west-2b	
gateways, NAT gateways,		chanmurth-private2-us-asst-2h	

Web Agent Benchmarks

Simulators (with simplified sites and tasks)

World of Bits: An Open-Domain Platform for Web-Based Agents

Tianlin (Tim) Shi¹² Andrej Karpathy² Linxi (Jim) Fan¹ Jonathan Hernandez² Percy Liang¹



- Simplified tasks, but comes with a simulator (can act, explore do RL).
- Introduced in 2017, remained challenging for some time afterward!

Real Sites and Tasks (but without simulators)

MIND2WEB: Towards a Generalist Agent for the Web

Xiang Deng* Yu Gu Boyuan Zheng Shijie Chen Samuel Stevens Boshi Wang Huan Sun* Yu Su* The Ohio State University https://osu-nlp-group.github.io/Mind2Web



- 2000 crowdsourced tasks and trajectories from ~100 real and diverse websites.
- Can perform reference-based evaluation, but lacks a simulator to allow agents to act freely.

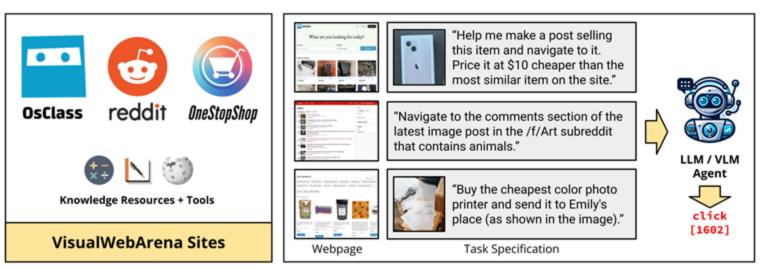
Simulators with Real-World Sites



Frank Xu

Shuyan Zhou

Jing Yu Koh



WebArena (Zhou*, Xu* et al., ICLR 2024) Standalone, self-hostable web environments VisualWebArena (Koh et al., ACL 2024) Benchmark for *multimodal* web agents

Reproducible Environments

POMDP environment: $\mathcal{E} = \langle S, A, O, T \rangle$ Observations O

Patio, Lawn & O	webarena.onestopshop.co Sarden	m	webarena.onestopshop.com		webarena.onestopshop.com	ho ty
	and the second se	NA NOR 1	<pre><div> <div> Outdoor Patio </div> Rating: <div> 82% </div> 12 Reviews </div></pre>	link img link Layou Sta gen lind Static butto butto	'ebArea 'Patio, Lawn' Image' Outdoor Patio' utTable '' ticText 'Rating:' teric '82%' < '12 Reviews' Text '549.99' n 'Add to Cart' focusable: True n 'Mish List' focusable: n 'Compare' focusable:	pro nev tal tal goi go. go. sci

Actions \mathcal{A}^{-}

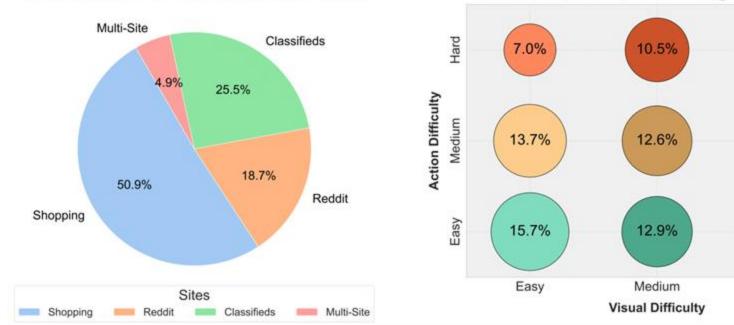
Action Type a	Description
click [elem]	Click on element elem.
hover [elem]	Hover on element elem.
type [elem] [text]	Type text on element elem.
press [key_comb]	Press a key combination.
new_tab	Open a new tab.
tab_focus [index]	Focus on the i-th tab.
tab_close	Close current tab.
goto [url]	Open url.
go_back	Click the back button.
go_forward	Click the forward button.
scroll [up down]	Scroll up or down the page.
stop [answer]	End the task with an optional output.

Execution-based evaluation $r(\mathbf{a},\mathbf{s})$ (reward) function:

Execution-Based Evaluation

Webpage / Input	Image(s)	Example Intent	Reward Function $r(s, a)$ Implementation		
And a loss of a second	A desta di Assessanti Regione di Assessanti Assessanti Assessanti Assessanti Assessanti	What is the ISIN of the company that occupies the largest portion in Warren Buffet's portfolio? An- swer using the information from the Wikipedia site in the second tab.	exact_match(â, "US0378331005")		
		Add something like what the man is wearing to my wish list.	<pre>url="/wishlist" locator(".wishlist .product-image-photo") eval_vqa(s, "Is this a polo shirt? (yes/no)", "yes") eval_vqa(s, "Is this shirt green? (yes/no)", "yes")</pre>		

VisualWebArena: Task Distribution



Distribution of Tasks Across Sites

Distribution of Tasks by Difficulty

14.8%

8.5%

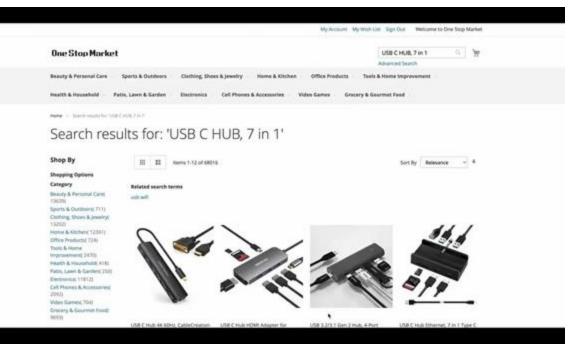
4.2%

Hard





Task: "Please add to my shopping cart all the items from this page that can connect these devices from the two images."

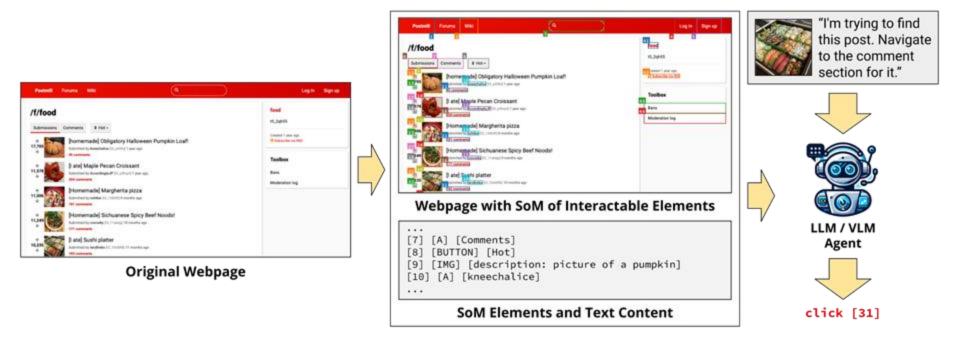




Jing Yu Koh

Building Multimodal LLM Agents

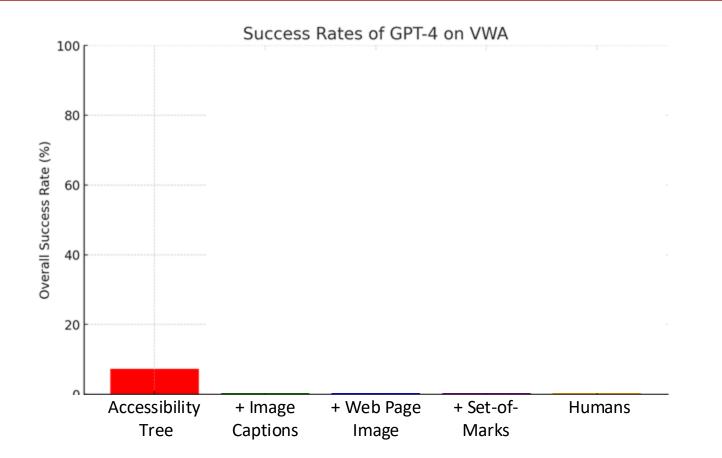
(Multimodal) LLMs as Agents





(venv) jingyuk@GS22433 visualwebarena % python run_demo.py \ --instruction path agent/prompts/jsons /p_som_cot_id_actree_3s.json \ --start_url "https://www.google.com/" --intent "Make a reservation at Pusade e's Garden for 2 people on the earliest date at any time. Use my name JY Koh and phone number 650-555-5555." \ --result dir demo test yelp \ --model gpt-4-vision-preview \ --action_set_tag som --observation_ty pe image_som \ --render

(Multimodal) LLMs as Agents



Common Failure Modes

• Failures in visual processing

- Clicking the wrong item
- Identifying specific items in complex webpages
- Spatial reasoning ("what are the prices of products in the first row?")

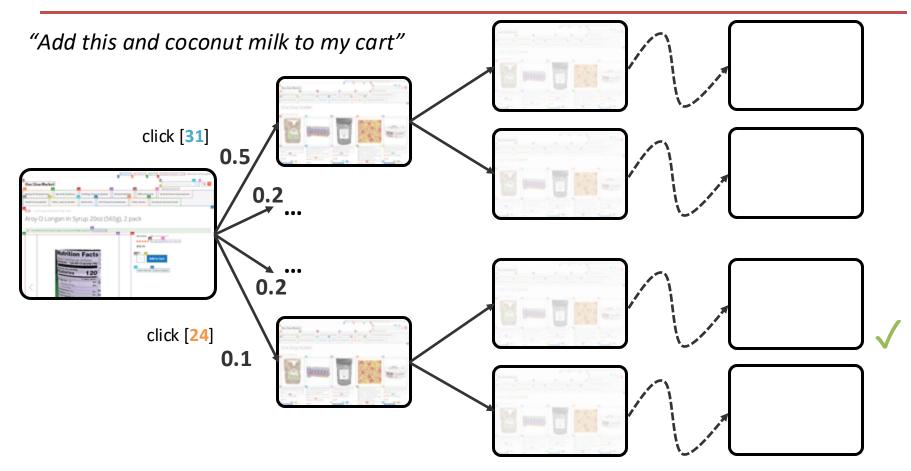
• Long horizon reasoning and planning

- Getting stuck in loops
- Correctly performing tasks but undoing them

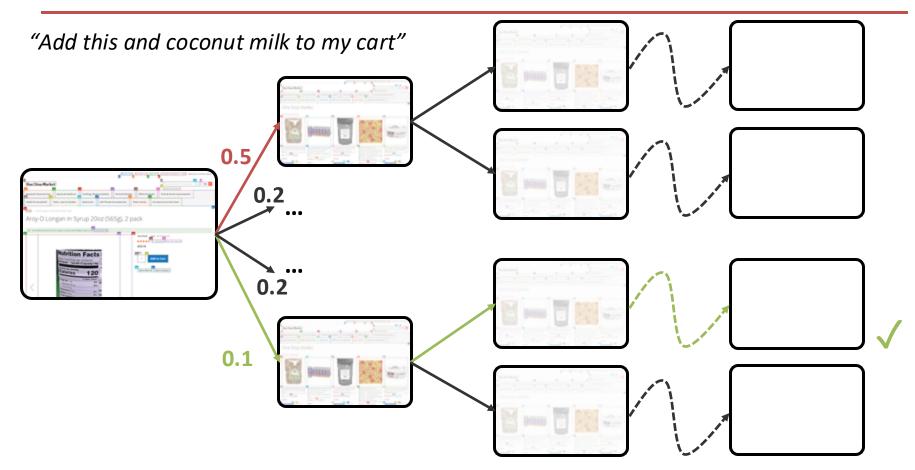
Exponential Error Compounding in Agents

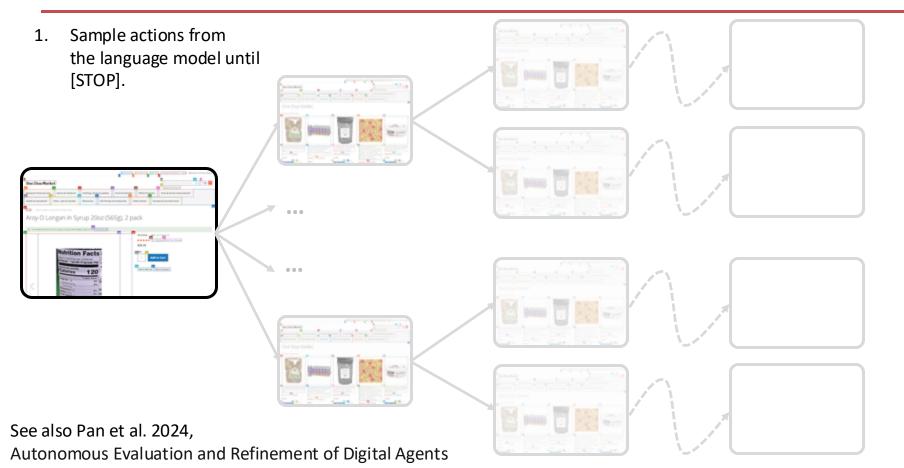
Accuracy @ k steps:						
1 (single step)	5	10	30	50		
90%	59.05%	34.87%	4.24%	0.52%		
95%	77.38%	59.87%	21.46%	7.69%		
99%	95.10%	90.44%	73.97%	60.50%		
99.9%	99.50%	99.00%	97.04%	95.12%		
99.99%	99.95%	99.90%	99.70%	99.50%		

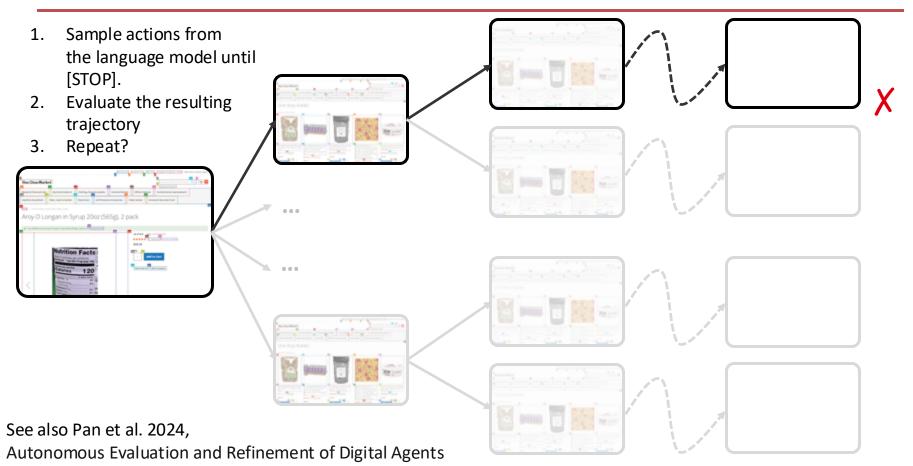
Local Decisions; Global Consequences

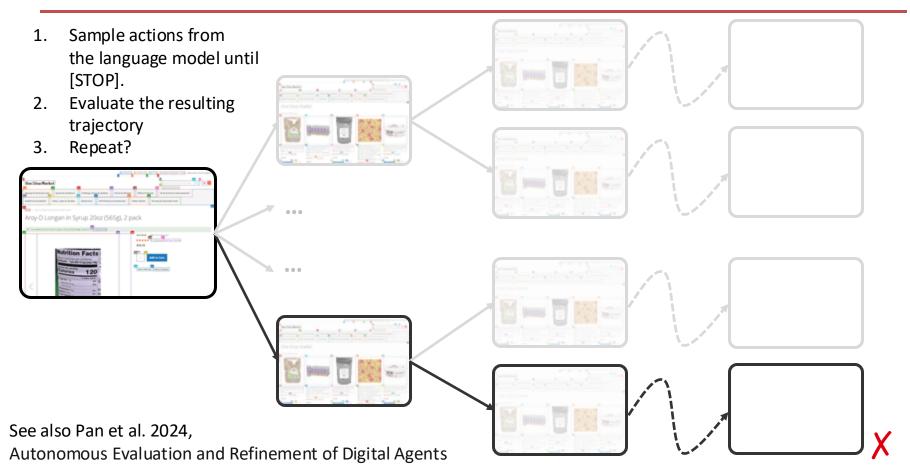


Local Decisions; Global Consequences

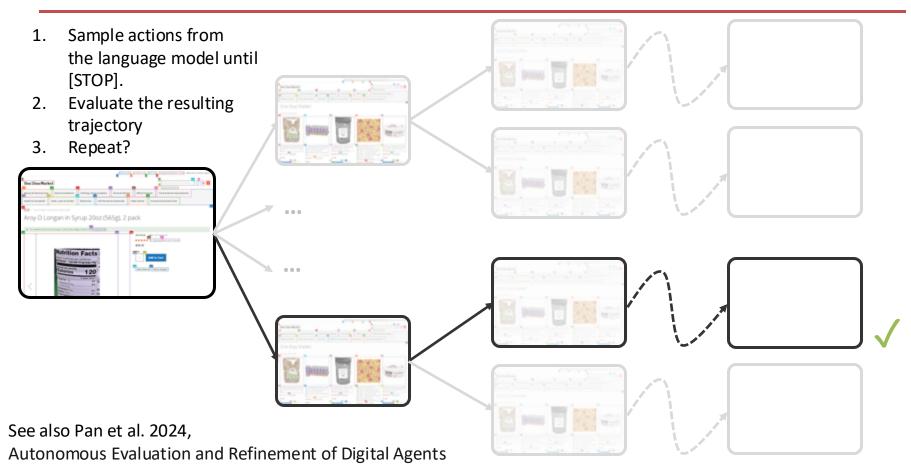




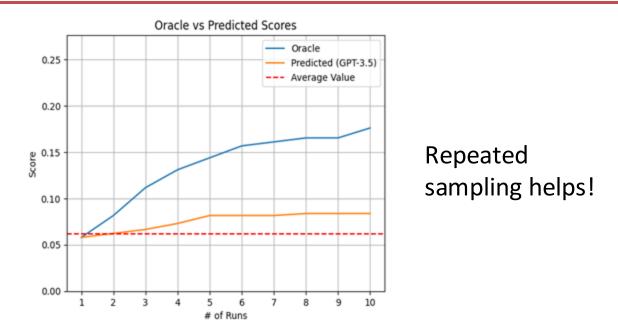




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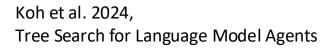
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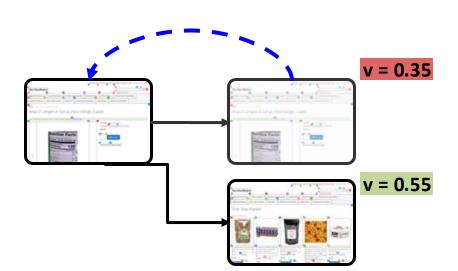


- But the space is exponentially large. Can we guide exploration?
- Key idea of our approach: apply value function to intermediate nodes.

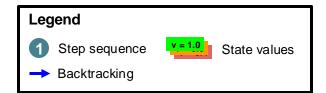
Our Method: Tree Search

- Best-first search algorithm
- Ingredients:
 - Baseline agent to propose actions.
 - Way to backtrack in the environment.
 - A value function to score and rerank candidate states.
 - In this work, we prompt GPT-40 to act as an evaluator.









GPT-40 Agent

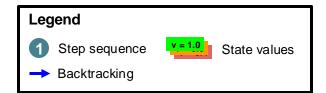


GPT-40 Agent + Search



Starting State

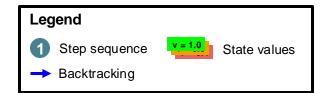




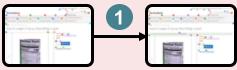








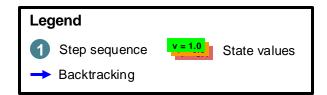
GPT-40 Agent





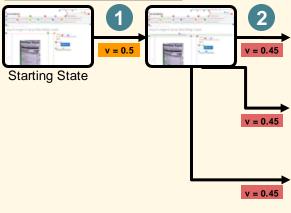
Starting State



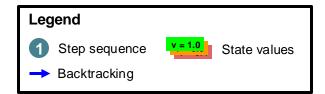


GPT-40 Agent



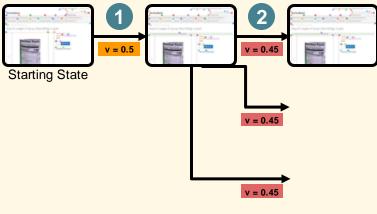




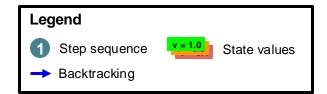


GPT-40 Agent



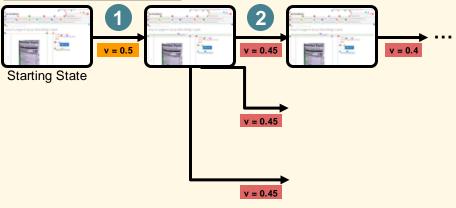






GPT-40 Agent

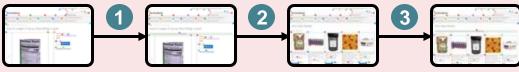


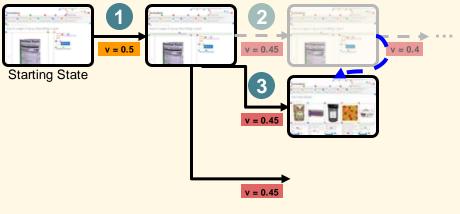






GPT-40 Agent



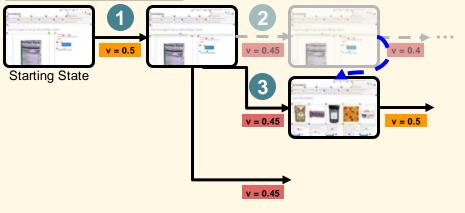




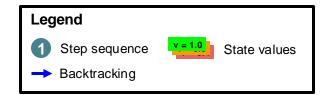


GPT-40 Agent



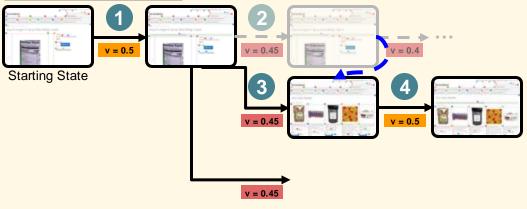




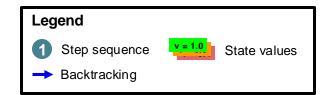


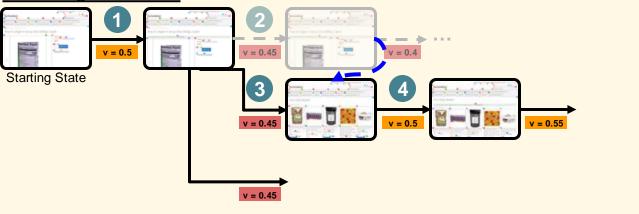
GPT-40 Agent



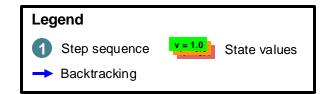












$\underbrace{\mathsf{GPT-4o Agent}}_{\texttt{I}} \underbrace{1}_{\texttt{I}} \underbrace{2}_{\texttt{I}} \underbrace{3}_{\texttt{I}} \underbrace{4}_{\texttt{I}} \underbrace{4}_{\texttt{Failure}} \underbrace{4}_{\texttt{$







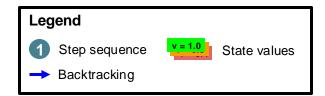






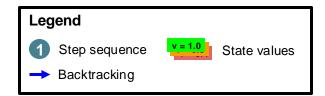






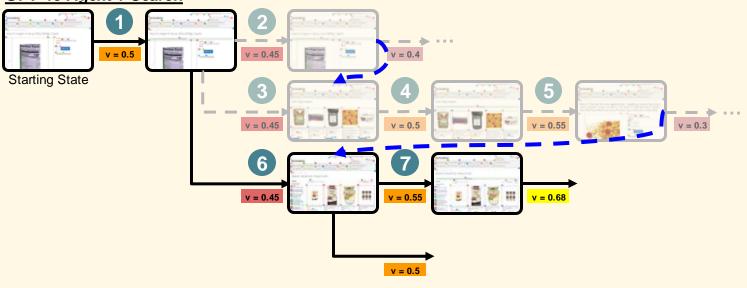




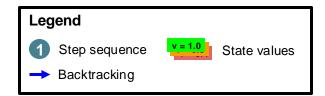


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GPT-40 Agent 3 2 4 TORN. ----Failure 10 1 1 Beans. 1





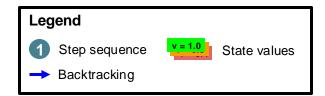


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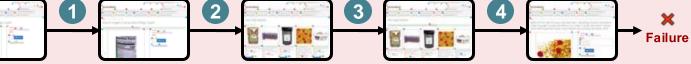
GPT-40 Agent 3 2 4 100.0 ----Failure -1 BRIDDE. 1

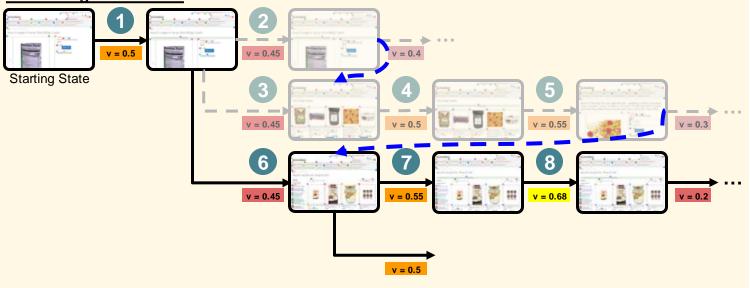




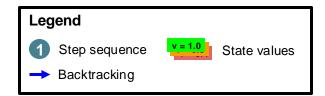


GPT-40 Agent 3 2 100.0













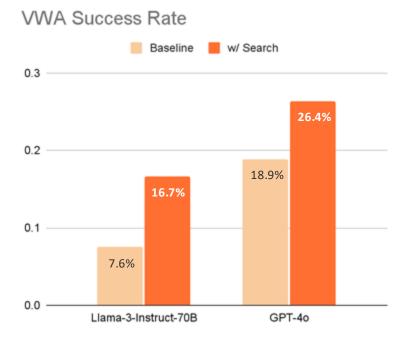


GPT-40 Agent





Results



WA Success Rate Baseline 📕 w/ Search 0.3 -0.2 19.2% 15.0% 0.1 -10.1% 7.6% 0.0 Llama-3-Instruct-70B GPT-40

Ablations

${\bf Depth}\; d$	$\mathbf{Branch}\; b$	SR (†)	Δ
0	1	24.5%	0%
1	3	26.0%	+6%
1	5	32.0%	+31%
2	3	31.5%	+29%
2	5	35.0%	+43%
3	5	35.5%	+45%
5	5	37.0%	+51%

Success rate (SR) and relative change over the baseline (Δ) on a subset of 200 VWA tasks with varying search depth (d) and branching factor (b). d = 0 indicates no search is performed. All methods use a max search budget c = 20.

Ablations

- Having a good value function is essential!
- There is still a lot of headroom for improving both the base agent policy, and the value function

Value Function	SR (†)
None (no search)	24.5%
LLaVA-v1.6-34B	30.0%
GPT-40 (no SC)	28.5%
GPT-4o	37.0%
Groundtruth	43.5%

Table 3: Success rate of the GPT-40 agent with different value functions.

Qualitative Results



Task Instruction (*I***):** "I recall seeing this exact item on the site, help me find the most recent post of it. I recall seeing it in either the Collectibles or Antiques section."

GPT-40 Agent + Search v = 0.5v = 0.53v = 0.45Starting State 3 v = 0.53v = 0.2v = 0.635 6 mentioned later page of Success v = 1.0v = 0.63v = 1.0 Legend: Search sequence --> Backtracking State values

Limitations

- Search is slow
 - We implemented backtracking in a relatively naive way (store actions in a queue, take them again to get to the original state)
 - See Chen et al. 2024, When is Tree Search Useful?
- Dealing with destructive actions
 - Some things on the web are very difficult to undo, e.g., ordering an item

Future Work

- Search as a policy improvement function.
- What's the value of value functions?
- What if we don't have a perfect simulator?
- Search to improve safety.

Adversarial Attacks on Multimodal Agents

Chen Henry Wu, Jing Yu Koh, Ruslan Salakhutdinov, Daniel Fried, Aditi Raghunathan Carnegie Mellon University {chenwu2,jingyuk,rsalakhu,dfried,aditirag}@cs.cmu.edu



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Po Yu Huang



Lawrence Jang



Jing Yu Koh



Ming Chong Lim



Robert Lo



Stephen McAleer



Graham Neubig



Russ Salakhutdinov



Frank Xu



Shuyan Zhou

Thanks!

{dfried,jingyuk,rsalakhu}@cs.cmu.edu jykoh.com/vwa // jykoh.com/search-agents



Reddit

Off topic but if the implementation of ethanol in the US was really about climate change, weld import sugar care

R Wkipedia G

Asia

Asia (rags, rejs) is bend is Earth's largest and most populous continent, located primary in the Eastern and Northern Hemispheres. It shares the continental landmass of Eurasia with the continent of Europe, and the continental landmass of Abs-Eurasia with Abrica and Europe. Asia covers in ama of 44,579,000 square klometers (17,272,000 square), about 29% of Earth's total land area and 8,7% of the Earth's total surface area. The continent, which has long been home to the majority of the human population.¹⁰ was the site of many of the first civilizations, its 4.7 billion people³⁶ constitutes roughly 60% of the world's population.¹¹

194

44.579.000 km²

Podulatio

GOP (PPP)

density

(17,212,000 sq mil (149¹¹)

100 km² (265 km mil)

4,560,667,108 (2018; 1+0-111

\$72,7 trillion (2022 est; 1x0

\$30 trillion (2022 est; 1+0

ta \$8,800 (2022 est 4214

Islam (06.1%)¹⁷

Hindulars 05.7%PT

This article is abled the continent. For other costs, not Asia (shambiguators)

In general terms, Asia is bounded on the east by the Pacific Ocean, on the south by the Indian Ocean, and on the north by the Arctic Ocean. The boother of Asia with Europe is a historical and outural combuct, as there is no clear physical and geographical separation between them. It is somewhat arbitrary and has moved since its first conception in classical antiquity. The devision of Eurosa into two continents reflects East-West outhansi, Inguistic, and ethnic differences, some of which vary on a spectrum rather than with a sharp dividing line. A commonly accepted division places Asia to the east of the Suiz Cana's separating it from Africa; and to the east of the Turkish Strates, the Unit Mountains and Data Rive, and to the south of the Cauciasus Mountains and the Caspian and Black Seas, separating it from Europ.^[11]

Chrise and India alternated in being the largest economies in the world from 5 to 1800 CE: Chrise was a major economic power and attracted many to the east[121214] and for many the legendary weakh and properly of the ancient outrue of India personited Asia,¹⁵⁸ attracting European commerce, exploration and coloniation. The accidents discovery of a trans-Atlantic route from Europe to America by Columbus while in search for a route to india demonstrates this deep fascination. The Sit Road became the main



Task: "What is the 2022 total nominal GDP of the area that produces most sugarcane in the year of 2021? (in billion)?"

Results

Benchmark	Agent Model	Max Actions	No Search	+ Search	Relative Change
VisualWebArena	GPT-40 + SoM ^[1]	30	19.8%	-	-
	Llama-3-70B-Instruct ^[1]		9.8%	-	-
	Llama-3-70B-Instruct (ours)	5	7.6%	16.7%	+119.7%
	GPT-4o + SoM (ours)		18.9%	26.4%	+39.7%
WebArena	GPT-40 ^[2]	30	13.1%	-	
	GPT-4 + Reflexion [3]		15.6%	-	-
	AutoWebGLM ^[4]		18.2%	-	-
	AutoEval ^[3]		20.2%	-	-
	BrowserGym (GPT-4) ^[5]		23.5%	-	-
	SteP [6]		35.8%	-	-
	GPT-4o (ours)	5	15.0%	19.2%	+28.0%

Model Type	LLM Backbone	Visual Backbone	Inputs		Success I	Rate (†)	
	ELM Dackbone	Visual Dackbolic	inputs	Classifieds	Reddit	Shopping	Overall
	LLaMA-2-70B			0.43%	1.43%	1.29%	1.10%
	Mixtral-8x7B			1.71%	2.86%	1.29%	1.76%
Text-only	Gemini-Pro	-	Acc. Tree	0.85%	0.95%	3.43%	2.20%
-	GPT-3.5			0.43%	0.95%	3.65%	2.20%
	GPT-4			5.56%	4.76%	9.23%	7.25%
	LLaMA-2-70B BLIP-2-T5XL	0.00%	0.95%	0.86%	0.66%		
	Mixtral-8x7B	BLIP-2-T5XL	Acc. Tree + Caps	1.28%	0.48%	2.79%	1.87%
Continue and the	GPT-3.5	LLaVA-7B		1.28%	1.43%	4.08%	2.75%
Caption-augmented	GPT-3.5	BLIP-2-T5XL		0.85%	1.43%	4.72%	2.97%
	Gemini-Pro	BLIP-2-T5XL		1.71%	1.43%	6.01%	3.85%
	GPT-4	BLIP-2-T5XL		8.55%	8.57%	16.74%	12.75%
	IDEFICS-	80B-Instruct		0.43%	0.95%	0.86%	0.77%
Multime del	Cog	VLM	Image I Cane I Ass. Tree	0.00%	0.48%	0.43%	0.33%
Multimodal	Gem	ini-Pro	Image + Caps + Acc. Tree	3.42%	4.29%	8.15%	6.04%
	GP	T-4V		8.12%	12.38%	19.74%	15.05%
	IDEFICS-	80B-Instruct		0.85%	0.95%	1.07%	0.99%
Multime del (CeM)	Cog	VLM	Internet Come & CoM	0.00%	0.48%	0.43%	0.33%
Multimodal (SoM)	Gem	ini-Pro	Image + Caps + SoM	3.42%	3.81%	7.73%	5.71%
	GP	T-4V		9.83%	17.14%	19.31%	16.37%
Human Performance	-	-	Webpage	91.07%	87.10%	88.39%	88.70%

Model Type	LLM Backbone	Visual Backbone	Inputs		Success Rate (↑)		
	ELM Dackbone	Visual Dackbone	inputs	Classifieds	Reddit	Shopping	Overall
	LLaMA-2-70B			0.43%	1.43%	1.29%	1.10%
	Mixtral-8x7B			1.71%	2.86%	1.29%	1.76%
Text-only	Gemini-Pro	-	Acc. Tree	0.85%	0.95%	3.43%	2.20%
-	GPT-3.5			0.43%	0.95%	3.65%	2.20%
	GPT-4			5.56%	4.76%	9.23%	7.25%
	LLaMA-2-70B	-2-70B BLIP-2-T5XL	0.00%	0.95%	0.86%	0.66%	
	Mixtral-8x7B	BLIP-2-T5XL	Acc. Tree + Caps	1.28%	0.48%	2.79%	1.87%
Contian augmented	GPT-3.5	LLaVA-7B		1.28%	1.43%	4.08%	2.75%
Caption-augmented	GPT-3.5	BLIP-2-T5XL		0.85%	1.43%	4.72%	2.97%
	Gemini-Pro	BLIP-2-T5XL		1.71%	1.43%	6.01%	3.85%
	GPT-4	BLIP-2-T5XL		8.55%	8.57%	16.74%	12.75%
	IDEFICS-	80B-Instruct		0.43%	0.95%	0.86%	0.77%
Multimedal	Cog	VLM	Image I Cana I Ass. Tree	0.00%	0.48%	0.43%	0.33%
Multimodal	Gem	ini-Pro	Image + Caps + Acc. Tree	3.42%	4.29%	8.15%	6.04%
	GP	T-4V		8.12%	12.38%	19.74%	15.05%
	IDEFICS-	80B-Instruct		0.85%	0.95%	1.07%	0.99%
Multimedal (SaM)	Cog	VLM	Image / Cane / SeM	0.00%	0.48%	0.43%	0.33%
Multimodal (SoM)	Gem	ini-Pro	Image + Caps + SoM	3.42%	3.81%	7.73%	5.71%
	GP	T-4V		9.83%	17.14%	19.31%	16.37%
Human Performance	-	-	Webpage	91.07%	87.10%	88.39%	88.70%

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Text-only	Gemini-Pro	-	Acc. Tree	0.85%	0.95%	3.43%	2.20%
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	GPT-4			5.56%	4.76%	9.23%	7.25%
LLaMA-2-70B BLIP-2-T5XL		0.00%	0.95%	0.86%	0.66%		
	Mixtral-8x7B	BLIP-2-T5XL	Acc. Tree + Caps	1.28%	0.48%	2.79%	1.87%
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Caption-augmented	GPT-3.5	BLIP-2-T5XL		0.85%	1.43%	4.72%	2.97%
	Gemini-Pro	BLIP-2-T5XL		1.71%	1.43%	6.01%	3.85%
	GPT-4	BLIP-2-T5XL		8.55%	8.57%	16.74%	12.75%
	IDEFICS-	80B-Instruct		0.43%	0.95%	0.86%	0.77%
Multimedal	Cog	VLM	Image I Cana I Asa Tras	0.00%	0.48%	0.43%	0.33%
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	GP	T-4V		8.12%	12.38%	19.74%	15.05%
	IDEFICS-	80B-Instruct		0.85%	0.95%	1.07%	0.99%
Multimedal (SeM)	Cog	VLM	Image / Cone / SeM	0.00%	0.48%	0.43%	0.33%
Multimodal (SoM)	Gem	ini-Pro	Image + Caps + SoM	3.42%	3.81%	7.73%	5.71%
	GP	T-4V		9.83%	17.14%	19.31%	16.37%
Human Performance	-	-	Webpage	91.07%	87.10%	88.39%	88.70%

Model Type	LLM Backbone	Visual Backbone	Inputs		Success I	Rate (†)	
	DEM Dackbone	Visual Dackbolic	inputs	Classifieds	Reddit	Shopping	Overall
	LLaMA-2-70B			0.43%	1.43%	1.29%	1.10%
	Mixtral-8x7B			1.71%	2.86%	1.29%	1.76%
Text-only	Gemini-Pro	-	Acc. Tree	0.85%	0.95%	3.43%	2.20%
-	GPT-3.5			0.43%	0.95%	3.65%	2.20%
	GPT-4			5.56%	4.76%	9.23%	7.25%
	LLaMA-2-70B	BLIP-2-T5XL		0.00%	0.95%	0.86%	0.66%
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Multimedal (SaM)	Cog	VLM	Image / Cane / SeM	0.00%	0.48%	0.43%	0.33%
Multimodal (SoM)	Gem	ini-Pro	Image + Caps + SoM	3.42%	3.81%	7.73%	5.71%
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	GPT-4	BLIP-2-T5XL		8.55%	8.57%	16.74%	12.75%
	IDEFICS-	80B-Instruct		0.43%	0.95%	0.86%	0.77%
Multime del	Cog	VLM	Image & Cana & Ass. Tree	0.00%	0.48%	0.43%	0.33%
Multimodal	Gem	ini-Pro	Image + Caps + Acc. Tree	3.42%	4.29%	8.15%	6.04%
	GP	T-4V		8.12%	12.38%	19.74%	15.05%
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Multimedal (SaM)	Cog	VLM	Imaga I Cana I SaM	0.00%	0.48%	0.43%	0.33%
Multimodal (SoM)	Gem	ini-Pro	Image + Caps + SoM	3.42%	3.81%	7.73%	5.71%
	GP	T-4V		9.83%	17.14%	19.31%	16.37%
Human Performance	-	-	Webpage	91.07%	87.10%	88.39%	88.70%

Ablations

- Search helps more for medium difficulty (4-9 actions to solve) tasks
- May be related to our own compute limitations: we fixed the max search depth to be 5 in our experiments
- Increasing the depth is likely to help hard tasks

Difficulty	No Search	Search	Δ
easy	34.2%	42.3%	+24%
medium	12.7%	22.2%	+75%
hard	10.2%	14.9%	+47%

Table 3: Success rates and relative change (Δ) of the GPT-40 agent on VWA tasks of different action difficulty levels.

Analysis

- Consistent gains across all site types
- Value function is already fairly general for web tasks

Website	No Search	Search	Δ
Classifieds	18.4%	26.5%	+44%
Reddit	17.1%	20.5%	+20%
Shopping	20.0%	29.0%	+45%
Overall	18.9%	26.4%	+40%

Table 4: Success rates and relative change (Δ) of the GPT-40 agent on VWA websites.

Website	No Search	Search	Δ
CMS	11.0%	16.5%	+50%
Map	21.1%	25.8%	+22%
Shopping	24.0%	28.1%	+17%
Reddit	7.9%	10.5%	+33%
Gitlab	10.2%	13.3%	+30%
Overall	15.0%	19.2%	+28%

Table 5: Success rates and relative change (Δ) of the GPT-40 agent on WA websites.

 Self-consistency chain-of-thought prompting (adapted from Pan et al. 2024), with 20 samples and values ranging from 0 to 1

system_message:

You are an expert in evaluating the performance of a web navigation agent. The agent is designed to help a human user navigate a website to complete a task. Given the user's intent, the agent's action history, the final state of the webpage, and the agent's response to the user, your goal is to decide whether the agent's execution is successful or not. If the current state is a failure but it looks like the agent is on the right track towards success, you should also output as such.

There are three types of tasks: